

Name: \_\_\_\_\_

Date: \_\_\_\_\_

# robotics

U E R C P Q S X Q X Z X F O B Q K P Y F J G I D  
Q H P D C H L Y B D B D N D L T I R S S B S D R  
C P C B Q D L H Y D R A U L I C X L D F N O H X  
R P L L J B P X W R X P A H E Y Q R P Z O F V A  
H U V R K M H H L U D X Y L F Z W R V Z I K M Y  
P G E W F K A G S I Z G A Q J R V O Y Y T I K L  
I J Z H X U D N I I H D E Z Y R W C R A A V T A  
W F R B K Z S I F T H D T E R L W J W W M H K D  
A C C I T A M U E N P X N E J F B K G W O U Y V  
Z J C B A C K P S R E T O O L I N G S W T W J Z  
P G W O R K E N V E L O P E H C T I P P U C O I  
V R O L L H R Z D C Z A D V N F Q X I R A F I Q  
R Q P L W S C I T O B O R R M M E R O B O T N X  
G P Y P K O T N D N Q N P L U W H A P V A C T H  
V D L W B Z Z P V D O C B V S T J S M Z M P E G  
V G W R H G A X E S B O N V W U B Y U T J X D X  
C R G E N R E T U P M O C U W J R W X R P E A G  
W I V Y W J T Q Q E L F I L J F W V C P W C R N  
I P U K L Z L C Y Q R K S Z M Z H C W S Y C M J  
Z P I M S M E F M B Q M P O G O Y L A M B W G F  
Q E S B J A N D R O I D U P T N B D Y F W K E H  
K R N U P H O T O S E N S O R K L D J G S E O B  
F A R T I F I C I A L I N T E L L I G E N C E H  
A U E E X Z U E J G N I L O O T M R A F O D N E

artificial intelligence  
photo sensor  
retooling  
computer  
android  
roll

end of arm tooling  
jointed arm  
hydraulic  
robotics  
pitch  
axes

work envelope  
automation  
pneumatic  
gripper  
robot  
yaw