

Name: _____

Date: _____

Robotics

G L L N V R T S T T M O T O R X G
N S O H D X N M O S B F P B S O T
F L J O V K E R B L E G O A C B T
U T W Y P X M O O J S E U G B I T
F Y H B J W H T R D W E R N E L C
M H C T P Q C S V L N X J G P R W
S F U Y C U A D S W I T C H E M M
S U L A O E T N D H Q G D K F D A
E U O R I I T I P D T U P N I R R
N W Y M L W A M J J R F F H M K G
S G B R O T A T I O N S L O Y W O
O D R J D N I A L G O R I T H M R
R Q I P M T O F M D Q O E V D K P
Y G C B P A W T Z V D N R D K D N
B B K P F W I B U C O L O U R P U
C E F G C I N O S A R T L U T R Y
C Q L S L D O H C U O T I B N I U

autonomous
rotations
Switch
Touch
lego

attachment
algorithm
Colour
Brick
Gyro

Mindstorms
degrees
Sensor
Motor
Loop

Ultrasonic
program
input
Robot