

Name: _____

Robotics

Q P E R G O N O M I C S I E A E C J H Q D U B M
T Y R A T O R M P N O Q M K C B T E C Y L Y B N
C E E F F E C T O R R Z S N L C J R D R I V E N
C N C T Y T Q N F H I E E E A E I M I A N C L X
I V S O U T Q W E Z L I L F N T H A E E V I D L
H I X N N P I V C R C E I U E B M T L S E R S T
P R B O N S N O R S E T D R R M B R O T R T J O
A O V M T O T I O G R L I O G H D I S H S E X R
R N M G S V I R F A H A E U M G L X N E E M W Q
G M G D E I A T A K R F B M F Z N L O T S O J U
O E Z N E A N N N I B A N N E T O M I I D S D E
H N N X I S R A N E N R T D L N I F S C X I Y N
T T T S Y R I T H O V T I I D S T Z N S B D G F
R Q R J A J E G T C T N S X O R A S E Q R C O A
O U A R M V D E N C E A I V H E V I M R G K L N
F E I E O H S B N L A M T C C N O M I Z K M O X
I Z N N Z B T Y T I K P P E C G N E D G A I N D
E I K G S Y O I S U G R M O O I N Y Q T S B H N
R L Z I O N L T R T P N U I N S I D H I E X C Y
U A C N T U J J I O E T E Z S E M E C U A A E Z
T U K E U G E N Q C G M U T U D A E O X A N T B
X S P E C K I X F O S L X O M W D Y J K X B M K
E I Y R M Y V H J I F P A U E K C I T S D R A Y
T V W S V E V A L U A T E J R B W S S E C O R P

orthographic
ergonomics
invention
artifact
evaluate
design
system
ruler

constraints
innovation
isometric
consumer
robotics
driven
torque
train

engineering
technology
mechanism
criteria
inverse
impact
force
gear

environment
algorithm
visualize
decision
process
matrix
input
math

aesthetics
designers
yardstick
effector
science
output
model

dimensions
engineers
annotate
elements
texture
rotary
ratio