

Name: _____

Date: _____

Part 1

V M E T S Y S T O B O R L A I R T S U D N I V W
K D E G R E E S O F F R E E D O M C K Q V P Y E
S C J Y I B C Y T I L I B I X E L F S O A S R O
L M U Y W Z R U V Y M F S E I R E R C W O I N X
K A J Z F H U C V C L L J Z J E M S I H P S R I
M C Z L F J O A V K I X A H D G N R T I W S Y C
X M G T F H S D N C O M B E M J M V O N I A U Y
I S P K Z A Y L N Y E P V H Z S F Y B D K H J Z
R Y X J X P G U G K I V M U M W A U O U W C N R
K S T O B O R L A I R T S U D N I F R S Y L O L
L J T F A X E Z D E P N L Y Y S S G L T X S I C
T G D P U P N N P G F E E D B A C K A R D U T P
C T Z P H K E M J N I A H A Z A R D I I E O O N
Q F A C T O R Y A U T O M A T I O N R A X M M X
C U R O S N E S L A N R E T N I P W T L T O S H
O V T C U Y A C H H I O E S E I Q X S E E N U X
J G A T E E N D E F F E C T O R T H U Q R O O M
D E Y A C U W Q L S L G I O J V C I D U I T D R
W Q E M E R G E N C Y S T O P G V T N I T U R R
N W A Y U X E W S M F Z K W M X I D I P Y A A V
A P C N Y L P R J H E K Q Y G P F B E M I U Z T
G U K Z X X V K E R Z E C B A Y F A X E U X A A
S B L D I G I T A L C O M P U T E R G N R U H D
N W C R W B A T J T Q T H T C M D D S T H B N W

Industrial Robot System
Factory Automation
Hazardous Motion
Emergency Stop
Flexibility
Feedback
CAD

Industrial Equipment
Degrees of Freedom
Digital Computer
Energy Source
Autonomous
Chassis
CAM

Industrial Robotics
Industrial Robot
Internal Sensor
End-Effector
Dexterity
Hazard