

Name: _____

Date: _____

Drones

N G K D A Y Z Y I R Y R O I B E W
R E A V R I X R Q U H K J P C E U
E C I I A K F S C I T O B O R L U
T N C O L L E A G U E S Q A V C K
P E D A G B G V G E R D K I E A R
O I J R H M Z O T B E M N I P T Y
C C A I O K L G R T W T V N Y S V
D S U P P N P L E I E K B O T B I
A B L O P B E C K N T R I A O O K
U U B B Y L T S S H M H F P T C F
Q O L P K I I I J B P Z M U O Y I
H C A F O G T C T J V D Y S R M V
D S H N W Y H N A R X P G O P F R
S Q R H C H R A M T T C U F D Q E
E Z V L F D U Z O T I K C Z D Q W
E T A G I V A N A I G O C P N A U
E L B A R E E T S N U K N Z N S G

application unsteerable algorithms colleagues
quadcopter detection intensity prototype
navigate obstacle robotics science
bypass drones