

Name: _____

Date: _____

Basic Robotics

X V D S I S S A H C R H N M M P M T H R I V M B
B E M E R G E N C Y S T O P G Y E N I O T O F F
Q J Y B Y F Z T R U J Q W G T G T E T S C N U I
V Q F Y S W X N X D U S A I X T S M E N X G C N
W E F U N N U U R L P N L F T I Y P R E V N D D
L Z N E E F G A T O L I Q A I Q S I A S X G J U
Y U T E J F Z Q E D B Q O C B S T U T L X I Y S
P K M D R A V T M I R E Z T J F O Q I A N S M T
N N Q T H G B K X O Q F N O O E B E O N O E O R
R T Y L O W Y E Y N P E Z R I E O L N R I D D I
Y Q E G J U L S K Y V I V Y N D R A E E T D E A
T W S C A F E Q O V P S T A T B L I N T O E E L
K Y Z R I J G J T U L X K U E A A R D N M D R R
F S R L Y V L J S C R S Y T D C I T E I S I F O
X C U M H R E S L I I C I O A K R S F X U A F B
E M W O C D D D E G Q T E M R D T U F S O R O O
F X N A M S J N G J Q U U A M S S D E C D E S T
P E O H Q O G A C N L W E T R K U N C L R T E I
N P M O L S N D E Q I G Y I O G D I T F A U E C
E M W X Z C O O U O F T C O B I N K O O Z P R S
H L N F B W M L T H O F I N O P I O R F A M G Z
A H J R C D C N B U N E B M T X N G M C H O E Q
E R X J C W S J V J A T K Q I K M A B N D C D V
T M S G B Z R J U J O Y K I B L D R R E L Z B E

Industrial Robot System
Industrial Robotics
Jointed Arm Robot
Internal Sensor
End-Effector
Iteration
Hazard

Computer-Aided Design
Factory Automation
Hazardous Motion
Emergency Stop
Flexibility
Feedback

Industrial Equipment
Degrees of Freedom
Limiting Device
Energy Source
Autonomous
Chassis