

Name: _____

Date: _____

Automation & Robotics

Y R S T X E U Y Z S K P Y X S J N S I O D O M D
T B U Z E R E G B F H V Z C A V I M P A C T O P
E G E T K T T T M Y E L E C T R I C T O B O R D
I H C L H Y R B T R O U B L E S H O O T L Z O Q
C D X I S Q A U T G X F U Z Y M J R C U S R X I
O D C C E V D W O R K F O R C E E W C W E E V L
S A Y G S I E A J I U L O X V M U S Y A E L Y P
L K A D L L O Z C C X T B U M V G L Y S U L R E
A I P O Y E F K V G C I W A S B L L B H I O A H
M C Z N C S F F H A D T R B V V P P T B T R J T
A E H Q E Q C R F V X G W M E P W P K G A T S E
R U K K L U P I A Q O N W O U J R H Z I A N R C
G T W B I G M P M R Z S O S R O O G A F U O E N
O L A Y M V N A P O Y A R I B K U A L I R C P A
R U J X I I V E T M N E Y O T B E B Z W A V R N
P A R G T Y D J H I W O T W E A I N J U J D O E
R A L K A Z G T U O C I C D R S M E V G U T G T
E O L L T G I V P F C O J E R G Y O N E W X R N
T F E P I R J T O S Y H J X O R V Q T D L Y A I
U G M F O N W L F Y I O Z J N W O U V U Y O M A
P A X G N F S R O T A L U P I N A M Y Q A X P M
M Q L Z A R O T C E F F E D N E W Y W S I L H E
O A S C N T C W C S R I J N Q K F R K Y I T K K
C D M P F R H Y D R A U L I C S H E N B H K J E

Computer program
Manipulators
Limitation
Trade-off
Economics
Society
Robot

Work envelope
End effector
Controller
Reprogram
Algorithm
Factory
Debug

Troubleshoot
Maintenance
Automation
Pneumatic
Robotics
Ethical

Power supply
Programmer
Workforce
Hydraulic
Electric
Impact